

Dynamic Memory Allocation: Basic Concepts

CSci 2021: Machine Architecture and Organization
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Your instructor: Stephen McCamant

Based on slides originally by:
Randy Bryant, Dave O'Hallaron, Antonia Zhai

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Today

- Basic concepts
- Implicit free lists

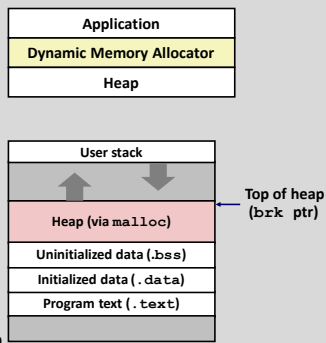
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Dynamic Memory Allocation

- Programmers use *dynamic memory allocators* (such as `malloc`) to acquire VM at run time.

- For data structures whose size is only known at runtime.

- Dynamic memory allocators manage an area of process virtual memory known as the *heap*.



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Dynamic Memory Allocation

- Allocator maintains heap as collection of variable sized *blocks*, which are either *allocated* or *free*
- Types of allocators
 - *Explicit allocator*: application allocates and frees space
 - E.g., `malloc` and `free` in C
 - *Implicit allocator*: application allocates, but does not free space
 - E.g. garbage collection in Java, ML, and Lisp
- Will discuss simple explicit memory allocation today

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The malloc Package

```
#include <stdlib.h>
```

```
void *malloc(size_t size)
```

- Successful:
 - Returns a pointer to a memory block of at least `size` bytes (typically) aligned to 8-byte boundary
 - If `size == 0`, may return NULL
- Unsuccessful: returns NULL (0) (on Unix, also sets `errno`)

```
void free(void *p)
```

- Returns the block pointed to by `p` to pool of available memory
- `p` must come from a previous call to `malloc` or `realloc`

Other functions

- `calloc`: Version of `malloc` that initializes allocated block to zero.
- `realloc`: Changes the size of a previously allocated block.
- `sbrk`: Used internally by allocators to grow or shrink the heap

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malloc Example

```
void foo(int n, int m) {
    int i, *p;

    /* Allocate a block of n ints */
    p = (int *) malloc(n * sizeof(int));
    if (p == NULL) {
        perror("malloc");
        exit(0);
    }

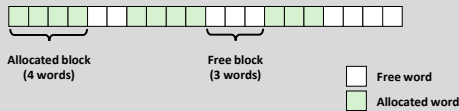
    /* Initialize allocated block */
    for (i=0; i<n; i++)
        p[i] = i;

    /* Return p to the heap */
    free(p);
}
```

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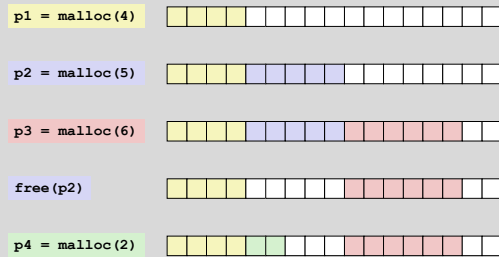
Assumptions Made in This Lecture

- Memory is word addressed (each word can hold a pointer)



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Allocation Example



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Constraints

- Applications**
 - Can issue arbitrary sequence of `malloc` and `free` requests
 - `free` request must be to a `malloc`'d block
- Allocators**
 - Can't control number or size of allocated blocks
 - Must respond immediately to `malloc` requests
 - i.e.*, can't reorder or buffer requests
 - Must allocate blocks from free memory
 - i.e.*, can only place allocated blocks in free memory
 - Must align blocks so they satisfy all alignment requirements
 - 8 byte alignment for GNU `malloc (libc)` on Linux boxes
 - Can manipulate and modify only free memory
 - Can't move the allocated blocks once they are `malloc`'d
 - i.e.*, compaction is not allowed

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Performance Goal: Throughput

- Given some sequence of `malloc` and `free` requests:
 - $R_0, R_1, \dots, R_M, \dots, R_{n-1}$
- Goals: maximize throughput and peak memory utilization
 - These goals are often conflicting
- Throughput:
 - Number of completed requests per unit time
 - Example:
 - 5,000 `malloc` calls and 5,000 `free` calls in 10 seconds
 - Throughput is 1,000 operations/second

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Performance Goal: Peak Memory Utilization

- Given some sequence of `malloc` and `free` requests:
 - $R_0, R_1, \dots, R_M, \dots, R_{n-1}$
- Def: Aggregate payload P_k**
 - `malloc(p)` results in a block with a *payload* of `p` bytes
 - After request R_k has completed, the *aggregate payload* P_k is the sum of currently allocated payloads
- Def: Current heap size H_k**
 - Assume H_k is monotonically nondecreasing
 - i.e.*, heap only grows when allocator uses `sbrk`
- Def: Peak memory utilization after k requests**
 - $U_k = (\max_{i \leq k} P_i) / H_k$

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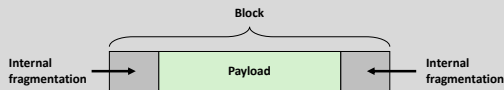
Fragmentation

- Poor memory utilization caused by *fragmentation*
 - internal* fragmentation
 - external* fragmentation

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Internal Fragmentation

- For a given block, *internal fragmentation* occurs if payload is smaller than block size

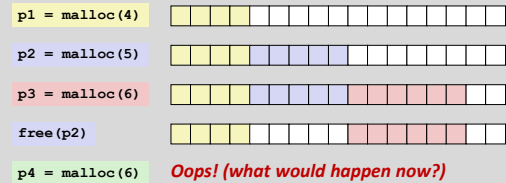


- Caused by
 - Overhead of maintaining heap data structures
 - Padding for alignment purposes
 - Explicit policy decisions (e.g., to return a big block to satisfy a small request)
- Depends only on the pattern of *previous* requests
 - Thus, easy to measure

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External Fragmentation

- Occurs when there is enough aggregate heap memory, but no single free block is large enough



- Depends on the pattern of future requests
 - Thus, difficult to measure

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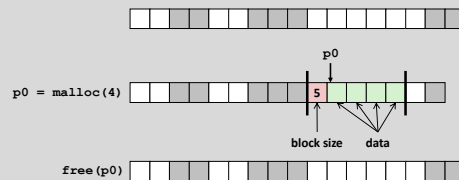
Implementation Issues

- How do we know how much memory to free given just a pointer?
- How do we keep track of the free blocks?
- What do we do with the extra space when allocating a payload that is smaller than the free block it is placed in?
- How do we pick a block to use for allocation -- many might fit?
- How do we reinsert a freed block?

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Knowing How Much to Free

- Standard method
 - Keep the length of a block in the word preceding the payload.
 - This word is often called the *header field* or *header*
 - Requires an extra word for every allocated block



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Keeping Track of Free Blocks

- Method 1: *Implicit list* using length—links all blocks



- Method 2: *Explicit list* among the free blocks using pointers



- Method 3: *Segregated free list*
 - Different free lists for different size classes
- Method 4: *Blocks sorted by size*
 - Can use a balanced tree (e.g. red-black tree) with pointers within each free block, and the length used as a key

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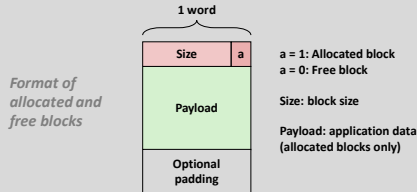
Today

- Basic concepts
- Implicit free lists

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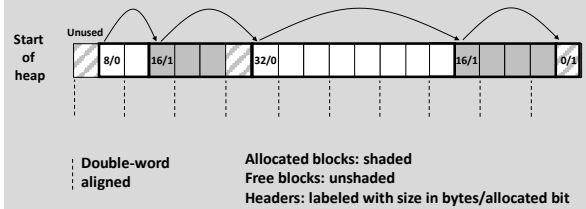
Method 1: Implicit List

- For each block we need both size and allocation status
 - Could store this information in two words: wasteful!
- Standard trick
 - If blocks are aligned, some low-order address bits are always 0
 - Instead of storing an always-0 bit, use it as a allocated/free flag
 - When reading size word, must mask out this bit



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Detailed Implicit Free List Example



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Implicit List: Finding a Free Block

- First fit:** Search list from beginning, choose *first* free block that fits:

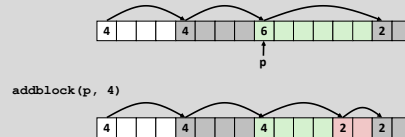
```
p = start;
while ((p < end) && // not passed end
      ((*p & 1) || // already allocated
       (*p <= len))) // too small
    p = p + (*p & -2); // go to next block (word addressed)
```

- Can take linear time in total number of blocks (allocated and free)
- In practice it can cause "splinters" at beginning of list
- Next fit:** Like first fit, but search list starting where previous search finished
- Should often be faster than first fit: avoids re-scanning unhelpful blocks
- Some research suggests that fragmentation is worse
- Best fit:** Search the list, choose the *best* free block: fits, with fewest bytes left over
- Keeps fragments small—usually helps fragmentation
- Will typically run slower than first fit

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Implicit List: Allocating in Free Block

- Allocating in a free block: **splitting**
 - Since allocated space might be smaller than free space, we might want to split the block



```
void addblock(ptr p, int len) {
    int newsize = ((len + 1) >> 1) << 1; // round up to even
    int oldsize = *p & -2; // mask out low bit
    *p = newsize | 1; // set new length
    if (newsize < oldsize)
        *(p+newsize) = oldsize - newsize; // set length in remaining
                                           // part of block
}
```

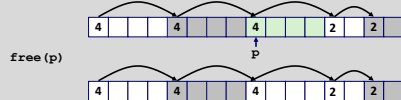
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Implicit List: Freeing a Block

- Simplest implementation:**
 - Need only clear the "allocated" flag

```
void free_block(ptr p) { *p = *p & -2; }
```

- But can lead to "false fragmentation"



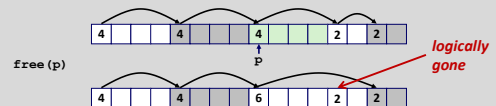
There is enough free space, but the allocator won't be able to find it

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Implicit List: Coalescing

- Join (**coalesce**) with next/previous blocks, if they are free

- Coalescing with next block



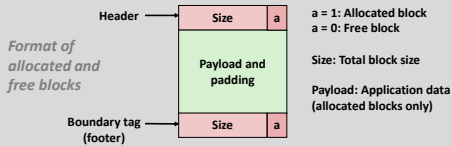
```
void free_block(ptr p) {
    *p = *p & -2; // clear allocated flag
    next = p + *p; // find next block
    if ((*next & 1) == 0)
        *p = *p + *next; // add to this block if
                          // not allocated
}
```

- But how do we coalesce with *previous* block?

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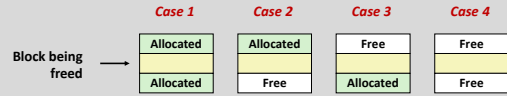
Implicit List: Bidirectional Coalescing

- **Boundary tags** [Knuth73]
 - Replicate size/allocated word at "bottom" (end) of free blocks
 - Allows us to traverse the "list" backwards, but requires extra space
 - Important and general technique!



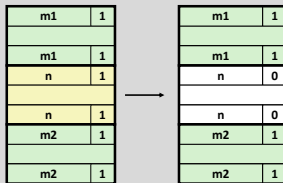
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Constant Time Coalescing



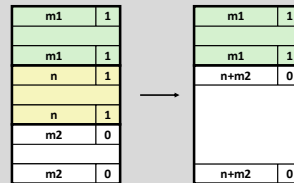
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Constant Time Coalescing (Case 1)



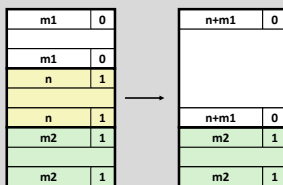
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Constant Time Coalescing (Case 2)



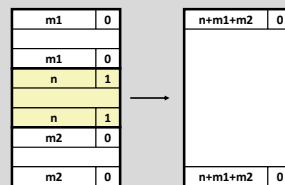
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Constant Time Coalescing (Case 3)



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Constant Time Coalescing (Case 4)



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Disadvantages of Boundary Tags

- **Internal fragmentation: wasted space for tags**
- **Can it be optimized?**
 - Which blocks need the footer tag?
 - We only coalesce with free blocks, so only free blocks need a footer
 - Idea: use footer only for free blocks
 - Same space can be used for payload if block is allocated
 - (Assume payload is not size 0)
 - If there's no footer, how do we know that the preceding block is free?
 - Use another low-order bit in the next block's header

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Summary of Key Allocator Policies

- **Placement policy:**
 - First-fit, next-fit, best-fit, etc.
 - Trades off lower throughput for less fragmentation
 - **Interesting observation:** segregated free lists (next lecture) approximate a best fit placement policy without having to search entire free list
- **Splitting policy:**
 - When do we go ahead and split free blocks?
 - How much internal fragmentation are we willing to tolerate?
- **Coalescing policy:**
 - **Immediate coalescing:** coalesce each time `free` is called
 - **Deferred coalescing:** try to improve performance of `free` by deferring coalescing until needed. Examples:
 - Coalesce as you scan the free list for `malloc`
 - Coalesce when the amount of external fragmentation reaches some threshold

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Implicit Lists: Summary

- **Implementation: very simple**
- **Allocate cost:**
 - linear time worst case
- **Free cost:**
 - constant time worst case, even with coalescing
- **Memory usage:**
 - will depend on placement policy
 - First-fit, next-fit or best-fit
- **Rarely used in practice for `malloc/free` because of linear-time allocation**
 - used in many special purpose applications
- **However, the concepts of splitting and boundary tag coalescing are quite general**

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